

## ■ 正誤表

「Scamper による ROS & Raspberry Pi 製作入門」（平成 30 年 12 月 21 日 第 1 刷）

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※ 計 3 か所

1. 【該当箇所】 p.36 1行目 コマンド入力	
誤	<pre>R \$ rosininstall_generator desktop --rostdistro kinetic --deps --wet-only -tar_ &gt; kinetic-desktop-wet.rosinstall R \$ wstool init src kinetic-desktop-wet.rosinstall</pre>
正	<pre>R \$ rosininstall_generator desktop --rostdistro kinetic --deps --wet-only -tar_ &gt; kinetic-desktop-wet.rosinstall R \$ wstool init src kinetic-desktop-wet.rosinstall</pre>
2. 【該当箇所】 p.85 下部 パッケージの実行	
誤	<p><b>【実行】</b></p> <pre>R \$ roscore ← 実行済みの場合、不要 R \$ rosruntime tutorial_topic subscriber_once R \$ rosruntime tutorial_topic publisher</pre>
正	<pre>R \$ roscore R \$ rosruntime tutorial_topic subscriber_async R \$ rosruntime tutorial_topic publisher</pre>

誤

CMakeLists.txt

```
cmake_minimum_required(VERSION 2.8.3)
project(tutorial_opencv)

find_package(catkin REQUIRED COMPONENTS
  roscpp
)
find_package(OpenCV 3 REQUIRED COMPONENTS
  opencv_core
  opencv_highgui
)

catkin_package()

include_directories(
  ${catkin_INCLUDE_DIRS}
  ${opencv_INCLUDE_DIRS}
)

set(TARGET "color2gray")
add_executable(${TARGET} src/${TARGET}.cpp)
target_link_libraries(${TARGET} ${catkin_LIBRARIES} ${opencv_LIBRARIES})
```

正

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project(tutorial_opencv)

find_package(catkin REQUIRED COMPONENTS
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)
find_package(OpenCV 3 REQUIRED COMPONENTS
  opencv_core
  opencv_highgui
  opencv_imgcodecs
)

catkin_package()

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  ${catkin_INCLUDE_DIRS}
  ${OpenCV_INCLUDE_DIRS}
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